

# An Automata-Based Approach to Games with $\omega$ -Automatic Preferences

CFV – Brussels (ULB)

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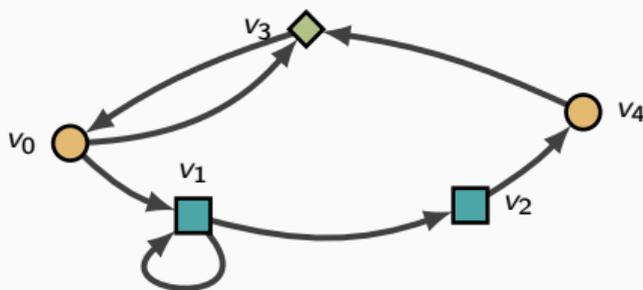
**Reactive systems:** **continuous interactions** between multiple **independent agents** with their own interests.



→ Ensure some specification under **rational** assumptions of agents.

# Game played on graphs

→ Model interactions with **games played on graphs**.

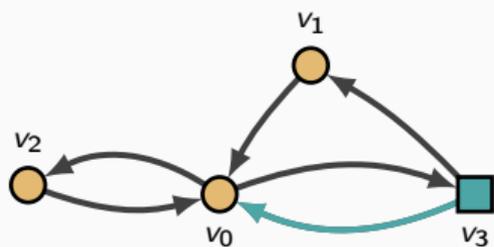


Directed graph:  $(V, E)$   
Set of players:  $\mathcal{P} = \{1, \dots, n\}$   
Partition of  $V$ :  $(V_i)_{i \in \mathcal{P}}$

} Arena  $A = (V, E, \mathcal{P}, (V_i)_{i \in \mathcal{P}})$

- **Play**:  $\pi \in \text{Plays} \subseteq V^\omega$  consistent with  $E$ , history:  $h \in V^*$ ,
- **Strategy** for  $i \in \mathcal{P}$ : function  $\sigma_i : V^* V_i \rightarrow V$ ,  $hv \mapsto \sigma_i(hv)$ .

# Games played on graphs



Can player  $\circ$  ensure the objective of **visiting**  $v_1$  from  $v_0$ ?

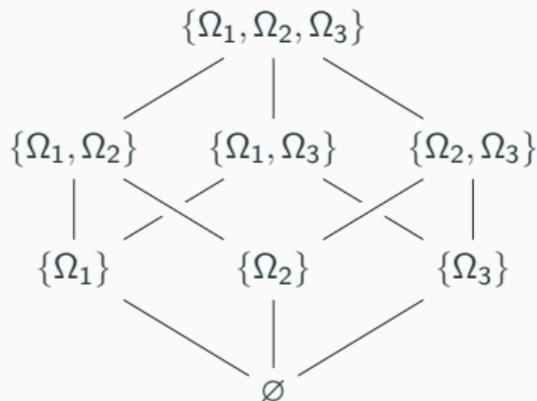
Classical setting: **objectives**  $\Omega_i : V^\omega \rightarrow \mathbb{Q}$ ,  
for each player  $i \in \mathcal{P}$  (e.g.,  $\Omega_i : V^\omega \rightarrow \{0, 1\}$ ).

Broader setting: **preference relations**

$\preceq_i \subseteq V^\omega \times V^\omega$  to compare plays:

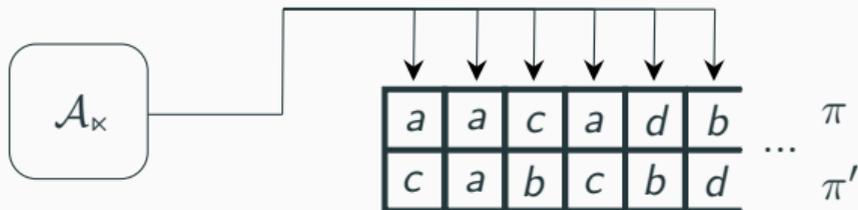
$\leadsto \pi \preceq_i \pi'$  if  $\pi'$  is **preferred** to  $\pi$ ,

e.g.,  $\pi \preceq_i \pi'$  if  $\Omega_i(\pi) < \Omega_i(\pi')$ .



## $\omega$ -Automatic Relations

$\leadsto$  Define  $\times$  with a **deterministic parity automaton** (DPW)  $\mathcal{A}_\times$  on the alphabet  $V \times V$  that **synchronously** reads two  $\omega$ -words.



$\mathcal{L}(\mathcal{A}) \subseteq (V \times V)^\omega$  can be seen as a binary relation:  **$\omega$ -automatic relation!**

### Examples (Alphabet $\Sigma = \{a, b\}$ )

- $\{(x, y) \mid \text{first}_a(x) \leq \text{first}_a(y)\}$  is  $\omega$ -automatic,
- $\{(x, y) \mid \text{for each prefix } u \text{ of } x, u[a \leftarrow aa] \text{ is a prefix of } y\}$  is **not**  $\omega$ -automatic ( $\leadsto$  need desynchronization).

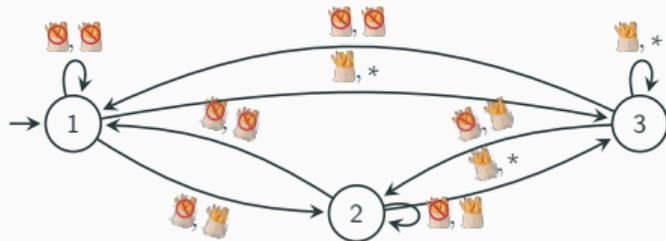
# Expressivity – Classical Objectives

$x \times y$  iff  $\Omega(x) < \Omega(y)$  (Boolean:  $\Omega(x) = 0$  and  $\Omega(y) = 1$ )

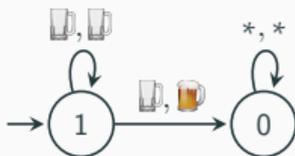
Reach()



Buchi()

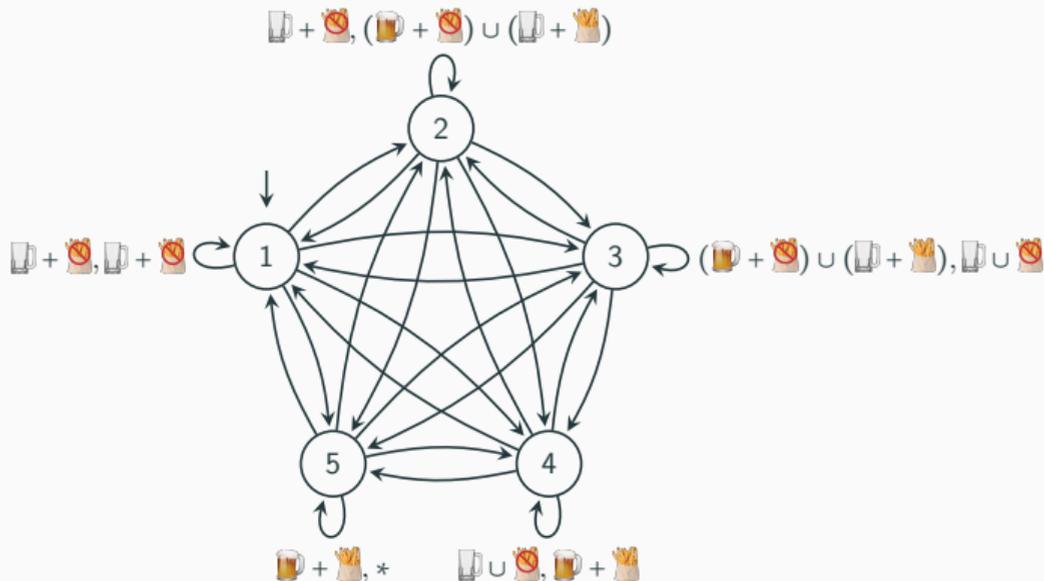


Reach() “as soon as possible”



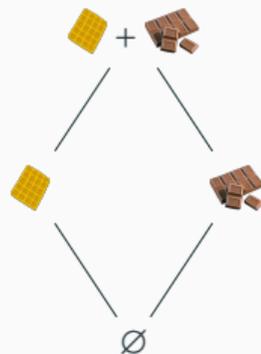
# Expressivity – Combinations of Classical Objectives

Counting order with two Büchi objectives (🍺 and 🍟).



# Expressivity – Combinations of Classical Objectives

**Subset order** with two reachability objectives (🟡, 🍫): 12 states.



## Theorem [Bansal, Chaudhuri, Vardi 2022]

- Limsup objectives:  $\omega$ -automatic.
- Discounted-Sum objectives:  $\omega$ -automatic iff the discount-factor is an integer  $d \in \mathbb{N}$ .
- Mean-Payoff objectives: **not**  $\omega$ -automatic.

# Zero-Sum Games

Zero-Sum: player 1 VS player 2.

## Threshold problem

Given a lasso  $\pi \in \text{Plays}(v_0)$ , does player 1 have a **winning strategy for the objective**  $\Omega = \{\rho \in V^\omega \mid \pi \times \rho\}$ ?

**Study values:**  $\text{Val}_1(v) = \{\pi \in \text{Plays}(v) \mid \exists \sigma_1 \forall \sigma_2, \pi \times \langle \sigma_1, \sigma_2 \rangle_v\}$

$\leadsto$  The threshold problem amounts to check  $\pi \in \text{Val}_1(v_0)$ .

**Optimal strategy:**  $\sigma_1^*$  such that  $\forall \pi \in \text{Val}_1(v), \forall \sigma_2, \pi \times \langle \sigma_1^*, \sigma_2 \rangle_v$ .

## Lemma

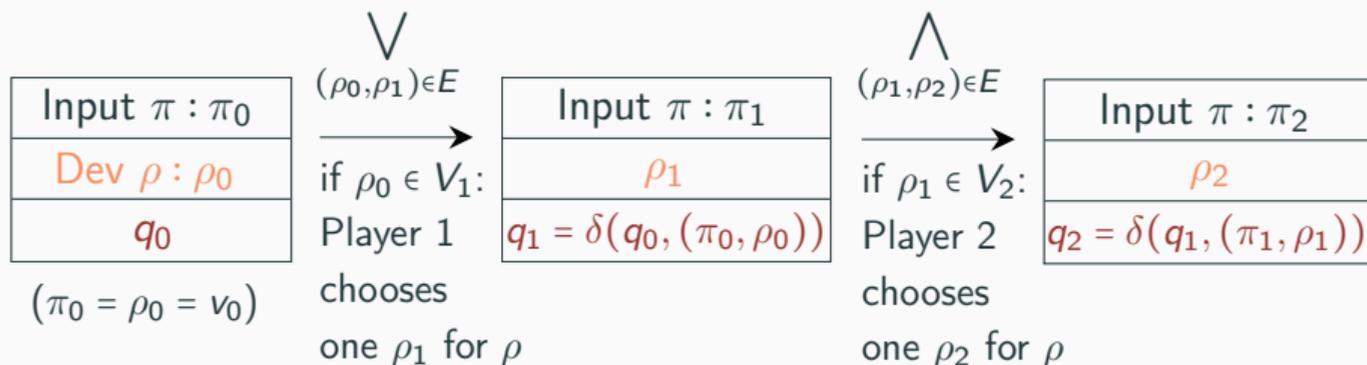
$\text{Val}_1(v)$  is accepted by a polysize **alternating** parity automaton (APW).

# Recognize $\text{Val}_1(v) = \{\pi \in \text{Plays}(v) \mid \exists \sigma_1 \forall \sigma_2, \pi \times \langle \sigma_1, \sigma_2 \rangle_v\}$

$\pi$ : Input

$\rho$ , player 1:  $\exists$

$\rho$ , player 2:  $\forall$



# Zero-Sum Games

Recall  $\text{Val}_1(v) = \{\pi \in \text{Plays}(v) \mid \exists \sigma_1 \forall \sigma_2, \pi \times \langle \sigma_1, \sigma_2 \rangle_v\}$ .

Given	Question	Equivalence	Complexity
$\pi$	Threshold prob. with $\pi$ ?	$\pi \in \text{Val}_1(v_0)$ ?	Parity-complete
$\pi, \sigma_1$	Threshold prob. with $\pi, \sigma_1$ ?	—	NL-complete
/	$\exists \pi$ , threshold prob. with $\pi$ ?	$\text{Val}_1(v_0) \neq \emptyset$ ?	PSPACE-complete
$\sigma_1$	Is $\sigma_1$ optimal?	$\neg(\text{Val}_1(v_0) \cap \sigma_1 \cap \dots = \emptyset)$ ?	PSPACE-complete
/	$\exists \sigma_1$ optimal?	Win. strat., obj. $\text{Val}_1(v_0)$ ?	2EXPTIME, PSPACE-h

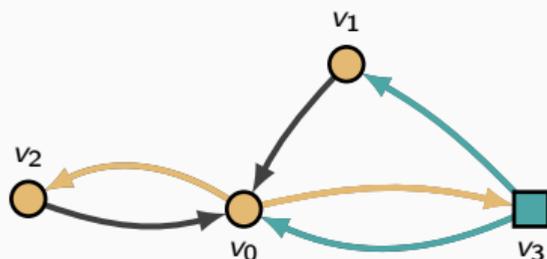
Let  $\text{Val}_{-1}(v) = \{\pi \in \text{Plays}(v) \mid \exists \sigma_2 \forall \sigma_1, \pi \not\times \langle \sigma_1, \sigma_2 \rangle_v\}$

$\rightsquigarrow \text{Val}_1(v) = \text{Plays}(v) \setminus \text{Val}_{-1}(v)$

## Beyond Zero-Sum: Non-Zero-Sum Games

A **Nash Equilibrium** (NE) is a strategy profile  $\sigma = (\sigma_i)_{i \in \mathcal{P}}$  from which no player has the incentive to **unilaterally deviate**, i.e.,

$$\forall i \in \mathcal{P}, \forall \tau_i \text{ strategy of player } i, \langle \sigma \rangle_{v_0} \not\prec_i \langle \sigma_{-i}, \tau_i \rangle_{v_0}.$$



- player  $\circ$  wants to visit  $v_1$ ,
- player  $\square$  wants to visit  $v_2$  inf. often.

Do there exist NEs from  $v_0$ ?

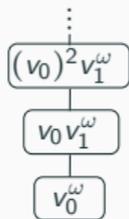
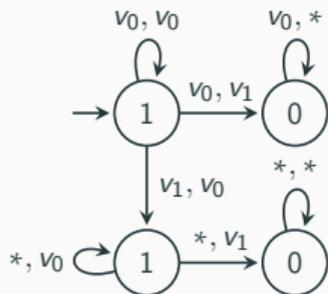
- 1)  $\sigma_{\square}(hv_3) = v_0$ ,  $\sigma_{\circ}(hv_0) = v_3$ .
- 2)  $\sigma'_{\square}(hv_3) = v_1$ ,  $\sigma'_{\circ}(hv_0) = v_2$  if  $v_1$  in  $h$ , else  $v_3$ .

NE 2) is **strictly better** than NE 1) for both players.

Does there **always** exist a Nash Equilibrium?

We can encode “**reachability as late as possible**”:

$\pi \times \pi'$  if  $\pi'$  visits  $v_1$  after  $\pi$ , or if  $\pi$  never visits  $v_1$ .



# Decision Problems

## NE Threshold problem

Given lassos  $(\rho_i)_{i \in \mathcal{P}}$ , does there exist an NE  $\bar{\sigma}$  such that  $\rho_i \times_i \langle \bar{\sigma} \rangle_{v_0}$  for all  $i \in \mathcal{P}$ ?

In general:  $\omega$ -regular constraint  $C \subseteq V^\omega$  given as an APW.

## Theorem

The NE threshold problem is PSPACE-complete.

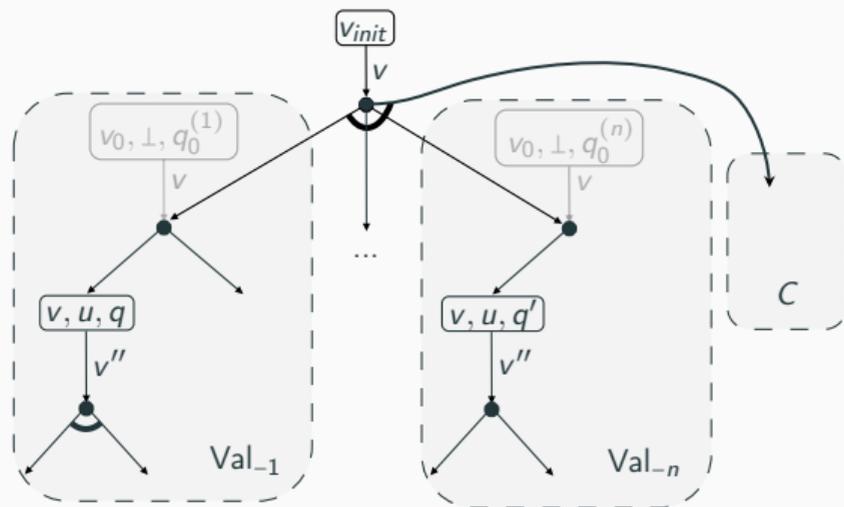
Improve the previous 2EXPTIME bound [Bruyère, G., Raskin 2025].

## Theorem

Deciding the existence of a Pareto-Optimal (maximal) NE outcome is in EXPSPACE and PSPACE-hard.

# NE Existence Problem in PSPACE

- Using value  $\text{Val}_{-i}(v) = \{\pi \in \text{Plays}(v) \mid \exists \sigma_{-i} \forall \sigma_i, \pi \not\prec_i \langle \bar{\sigma} \rangle_v\}$ ,
- We have  $\text{NE}_{\text{out}}(v) = \bigcap_{i \in \mathcal{P}} \text{Val}_{-i}(v)$ ,
- Compute  $C \cap \text{NE}_{\text{out}}(v)$  with **one universal transition**



$\leadsto$  Polynomial size, **emptiness** algorithm in PSPACE.

# Rational Synthesis (Stackelberg Game)

A special player, player 0, declares  $\sigma_0$  first and is **forbidden** to deviate.

Given a threshold lasso  $\pi \in \text{Plays}(v)$ ,

**Cooperative NE rational synthesis (CRS):**

$$\exists \sigma_0, \exists \sigma_0\text{-fixed NE } \bar{\sigma}, \quad \pi \times_0 \langle \bar{\sigma} \rangle_v.$$

**Non-cooperative NE rational synthesis (NCRS):**

$$\exists \sigma_0, \forall \sigma_0\text{-fixed NE } \bar{\sigma}, \quad \pi \times_0 \langle \bar{\sigma} \rangle_v.$$

## Theorem

The CRS problem is PSPACE-complete.

The NCRS problem is undecidable. (Reduction from the  $\omega$ -PCP problem)

## Future/Ongoing Work

- ~> Close the **complexity gaps** for optimal strategies and Pareto-Optimal NE (existential projection for APW requires non-determinism).
- ~> Main future work: extend to **subgame perfect equilibria (SPE)**.
- There are games with the existence of NEs but with **no SPE**.
  - Study **one-deviation immune** profiles, **weak SPEs**,
  - **Characterize** or decide the **existence** of (weak) SPE outcomes,
  - The **SPE existence** problem for **one-player games** is PSPACE-complete.

Thank you! Questions?

# Undecidability of Rational Synthesis

From  $\omega$ -PCP: Let  $\varphi_L, \varphi_R : A \rightarrow B^*$ , find  $a \in A^\omega$  such that  $\varphi_L(a) = \varphi_R(a)$ .

