

# As Soon as Possible but Rationally: Rational Synthesis for Reachability on Weighted Graphs

## Highlights'24

**Christophe Grandmont**

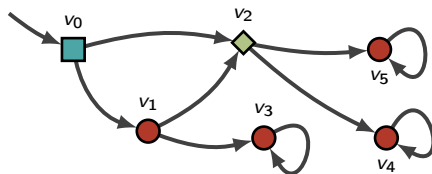


September 19, 2024  
Bordeaux, France

Work with Véronique Bruyère and Jean-François Raskin  
Published in CONCUR'24

# Multiplayer Reachability Games

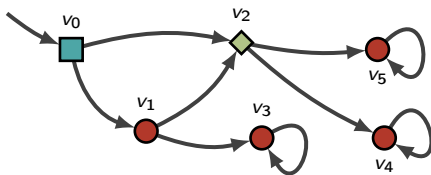
↪ Model interactions with (turn-based) **games played on graphs**



- Player 0: **system**, players 1, ...,  $t$ : **component of the environment...**

# Multiplayer Reachability Games

→ Model interactions with (turn-based) **games played on graphs**



- Player 0: **system**, players 1, ...,  $t$ : **component of the environment...**
- ...each with a **quantitative** reachability objective  $(T_i, w_i)$ :
  - $T_i \subseteq V$  a **target set**,
  - $w_i : E \rightarrow \mathbb{N}$  a **weight function**,

→ associate a **cost** to each play  $\pi = \pi_0\pi_1\pi_2\dots$ ,

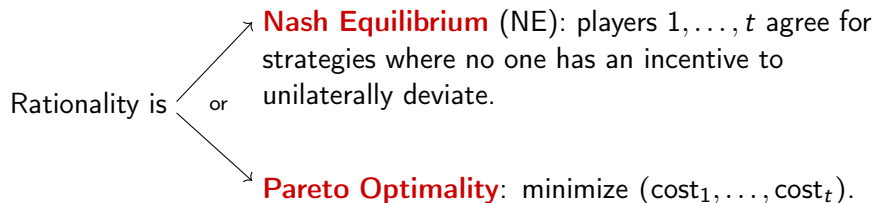
$$\text{cost}_i(\pi) = \begin{cases} \sum_{k=1}^n w_i((\pi_{k-1}, \pi_k)) & \text{for } n = \inf\{k \in \mathbb{N} \mid \pi_k \in T_i\} < +\infty, \\ +\infty & \text{if } n = +\infty. \end{cases}$$

# Rationality in Stackelberg Game

**Stackelberg game:** player 0 fixes a strategy  $\sigma_0$ , and we expect the environment to behave **rationally** according to  $\sigma_0$ .

# Rationality in Stackelberg Game


**Stackelberg game:** player 0 fixes a strategy  $\sigma_0$ , and we expect the environment to behave **rationally** according to  $\sigma_0$ .

Rationality is  or

- Nash Equilibrium (NE):** players  $1, \dots, t$  agree for strategies where no one has an incentive to unilaterally deviate.
- Pareto Optimality:** minimize  $(\text{cost}_1, \dots, \text{cost}_t)$ .


# Rationality in Stackelberg Game

**Stackelberg game:** player 0 fixes a strategy  $\sigma_0$ , and we expect the environment to behave **rationally** according to  $\sigma_0$ .

Rationality is  **Nash Equilibrium (NE):** players  $1, \dots, t$  agree for strategies where no one has an incentive to unilaterally deviate.

# Rationality in Stackelberg Game

**Stackelberg game:** player 0 fixes a strategy  $\sigma_0$ , and we expect the environment to behave **rationally** according to  $\sigma_0$ .

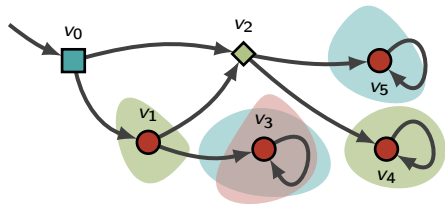
Rationality is  **Nash Equilibrium (NE):** players  $1, \dots, t$  agree for strategies where no one has an incentive to unilaterally deviate.

A strategy profile  $\sigma = (\sigma_0, \dots, \sigma_t)$  is an NE if for each player  $i$  ( $\neq 0$ ), each **strategy**  $\tau_i$  of  $i$  (called **deviating**),

$$\text{cost}_i(\langle \sigma \rangle) \leq \text{cost}_i(\langle \sigma_0, \dots, \sigma_{i-1}, \tau_i, \sigma_{i+1}, \dots, \sigma_t \rangle).$$

The play  $\langle \sigma \rangle$  is called an **NE outcome**.

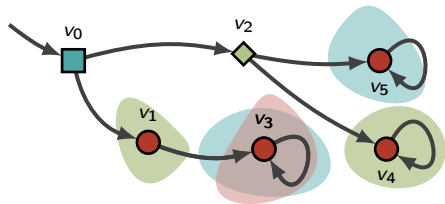
# Nash Equilibria in Stackelberg Game: Example



- All weights constant,  $w_i = 1$ ,
- $T_0 = \{v_3\}$ ,
- $T_{\square} = \{v_3, v_5\}$ ,
- $T_{\diamond} = \{v_1, v_4\}$ .



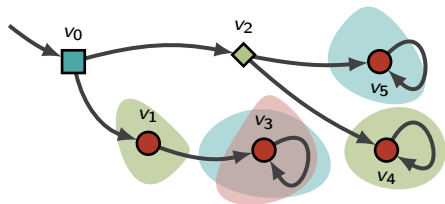
# Nash Equilibria in Stackelberg Game: Example



- All weights constant,  $w_i = 1$ ,
- $T_0 = \{v_3\}$ ,
- $T_{\square} = \{v_3, v_5\}$ ,
- $T_{\diamond} = \{v_1, v_4\}$ .

For  $\sigma_0$  such that  $\sigma_0(v_1) = v_3$ :

# Nash Equilibria in Stackelberg Game: Example



- All weights constant,  $w_i = 1$ ,
- $T_0 = \{v_3\}$ ,
- $T_{\square} = \{v_3, v_5\}$ ,
- $T_{\diamond} = \{v_1, v_4\}$ .

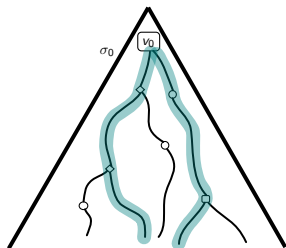
For  $\sigma_0$  such that  $\sigma_0(v_1) = v_3$ :

	player 0	player $\square$	player $\diamond$	NE outcome ?
$v_0 v_1 v_3$	2	2	1	Yes
$v_0 v_2 v_5$	$+\infty$	2	$+\infty$	No (player $\diamond$ : $v_2 \rightarrow v_4$ )
$v_0 v_2 v_4$	$+\infty$	$+\infty$	2	No (player $\square$ : $v_0 \rightarrow v_1$ )

# Rational Synthesis

The (non-cooperative) **Rational Synthesis** problem asks to decide whether there exists a strategy of player 0 such that every *rational* response of the environment *to this strategy* produces a play  $\pi$  with  $\text{cost}_0(\pi) \leq c$ , i.e.,

$$\exists \sigma_0, \forall \pi \in \text{Plays}_{\sigma_0}, \pi \text{ is an NE outcome} \Rightarrow \text{cost}_0(\pi) \leq c.$$



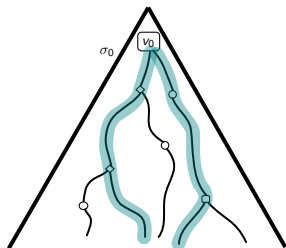
# Rational Synthesis

The (non-cooperative) **Rational Synthesis** problem asks to decide whether there exists a strategy of player 0 such that every *rational* response of the environment *to this strategy* produces a play  $\pi$  with  $\text{cost}_0(\pi) \leq c$ , i.e.,

$$\exists \sigma_0, \forall \pi \in \text{Plays}_{\sigma_0}, \pi \text{ is an NE outcome} \Rightarrow \text{cost}_0(\pi) \leq c.$$

→ Less restricted version: **Cooperative** Rational Synthesis:

$$\exists \sigma_0, \exists \pi \in \text{Plays}_{\sigma_0}, \pi \text{ is an NE outcome} \wedge \text{cost}_0(\pi) \leq c.$$



# All results

**Verification:** give  $\sigma_0$  as input through a nondeterministic or deterministic Mealy machine

---

<sup>1</sup>NEXPTIME-complete for a *common weight function*: Brihaye, Bruyère, and Reghem, “Quantitative Reachability Stackelberg-Pareto Synthesis is NEXPTIME-complete”, RP 2023.

<sup>2</sup>Bruyère, Raskin, and Tamines, “Stackelberg-Pareto Synthesis”, CONCUR 2021

<sup>3</sup>Condurache et al., “The Complexity of Rational Synthesis”, ICALP 2016

<sup>4</sup>Christophe Grandmont, Master’s Thesis 2023

# All results

**Verification:** give  $\sigma_0$  as input through a nondeterministic or deterministic Mealy machine

	Coop. synthesis	Non-coop. synthesis	Non-coop. verif. (det.)	Non-coop. verif. (nondet.)
Pareto, weights	PSPACE-complete	NEXPTIME-hard <sup>1</sup>	$\Pi_3^P$ -complete	PSPACE-complete
Pareto, qualitative	PSPACE-complete	NEXPTIME-complete <sup>2</sup>	$\Pi_2^P$ -complete	PSPACE-complete
Nash, weights	NP-complete	Unknown (EXPTIME-hard)	coNP-complete	coNP-complete
Nash, qualitative	NP-complete <sup>3</sup>	PSPACE-complete <sup>3</sup>	coNP-complete <sup>4</sup>	coNP-complete <sup>4</sup>
Pareto, weights in $\mathbb{Z}$	-	Undecidable	-	-
Nash, weights in $\mathbb{Z}$	-	Undecidable	-	-

<sup>1</sup>NEXPTIME-complete for a *common weight function*: Brihaye, Bruyère, and Reghem, “Quantitative Reachability Stackelberg-Pareto Synthesis is NEXPTIME-complete”, RP 2023.

<sup>2</sup>Bruyère, Raskin, and Tamines, “Stackelberg-Pareto Synthesis”, CONCUR 2021

<sup>3</sup>Condurache et al., “The Complexity of Rational Synthesis”, ICALP 2016

<sup>4</sup>Christophe Grandmont, Master’s Thesis 2023

# All results

**Verification:** give  $\sigma_0$  as input through a nondeterministic or deterministic Mealy machine

	Coop. synthesis	Non-coop. synthesis	Non-coop. verif. (det.)	Non-coop. verif. (nondet.)
Pareto, weights	PSPACE-complete	NEXPTIME-hard <sup>1</sup>	$\Pi_3^P$ -complete	PSPACE-complete
Pareto, qualitative	PSPACE-complete	NEXPTIME-complete <sup>2</sup>	$\Pi_2^P$ -complete	PSPACE-complete
Nash, weights	NP-complete	Unknown (EXPTIME-hard)	coNP-complete	coNP-complete
Nash, qualitative	NP-complete <sup>3</sup>	PSPACE-complete <sup>3</sup>	coNP-complete <sup>4</sup>	coNP-complete <sup>4</sup>
Pareto, weights in $\mathbb{Z}$	-	Undecidable	-	-
Nash, weights in $\mathbb{Z}$	-	Undecidable	-	-

# Thank you !

<sup>1</sup>NEXPTIME-complete for a *common weight function*: Brihaye, Bruyère, and Reghem, “Quantitative Reachability Stackelberg-Pareto Synthesis is NEXPTIME-complete”, RP 2023.

<sup>2</sup>Bruyère, Raskin, and Tamines, “Stackelberg-Pareto Synthesis”, CONCUR 2021

<sup>3</sup>Condurache et al., “The Complexity of Rational Synthesis”, ICALP 2016

<sup>4</sup>Christophe Grandmont, Master’s Thesis 2023